



# NAVISP-EI2-006

## Development of a Spaceborne GNSS Receiver

NAVISP Industry Days

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Dr. Cyril Botteron





### □ Background

- National leader in hardware and software electronic solutions for satellites
- Design and production of flight electronics for more than 25 years, 50 missions with 100% success

### □ Full in-house production facility, ESA qualified

- 250 m2 clean room
- Automatic pick & place and manual assembly / test

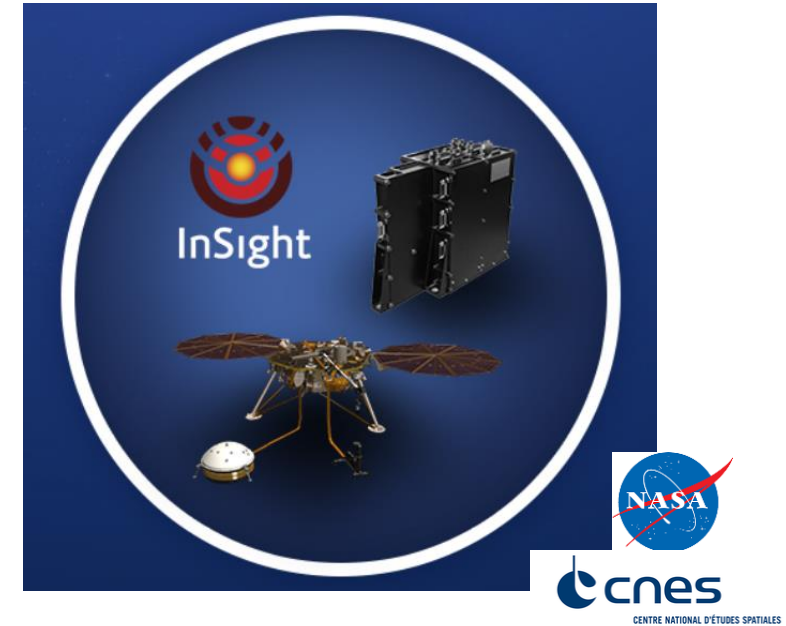
### □ Syderal Swiss SA

- Date of creation : 1942 under the name of CIR
- Part of ALCATEL Space between 1998 & 2003
- SYDERAL SA since 2003 : Management owned, Swiss SME
- 70 employees in Neuchâtel, Switzerland

### □ Syderal Group

- Subsidiary in Poland: **SYDERAL POLSKA** → Space el.
- Subsidiary in Switzerland :
  - **KEYCOM** → Laundry/Building management system
- Total of ~90 employee





## Data Handling

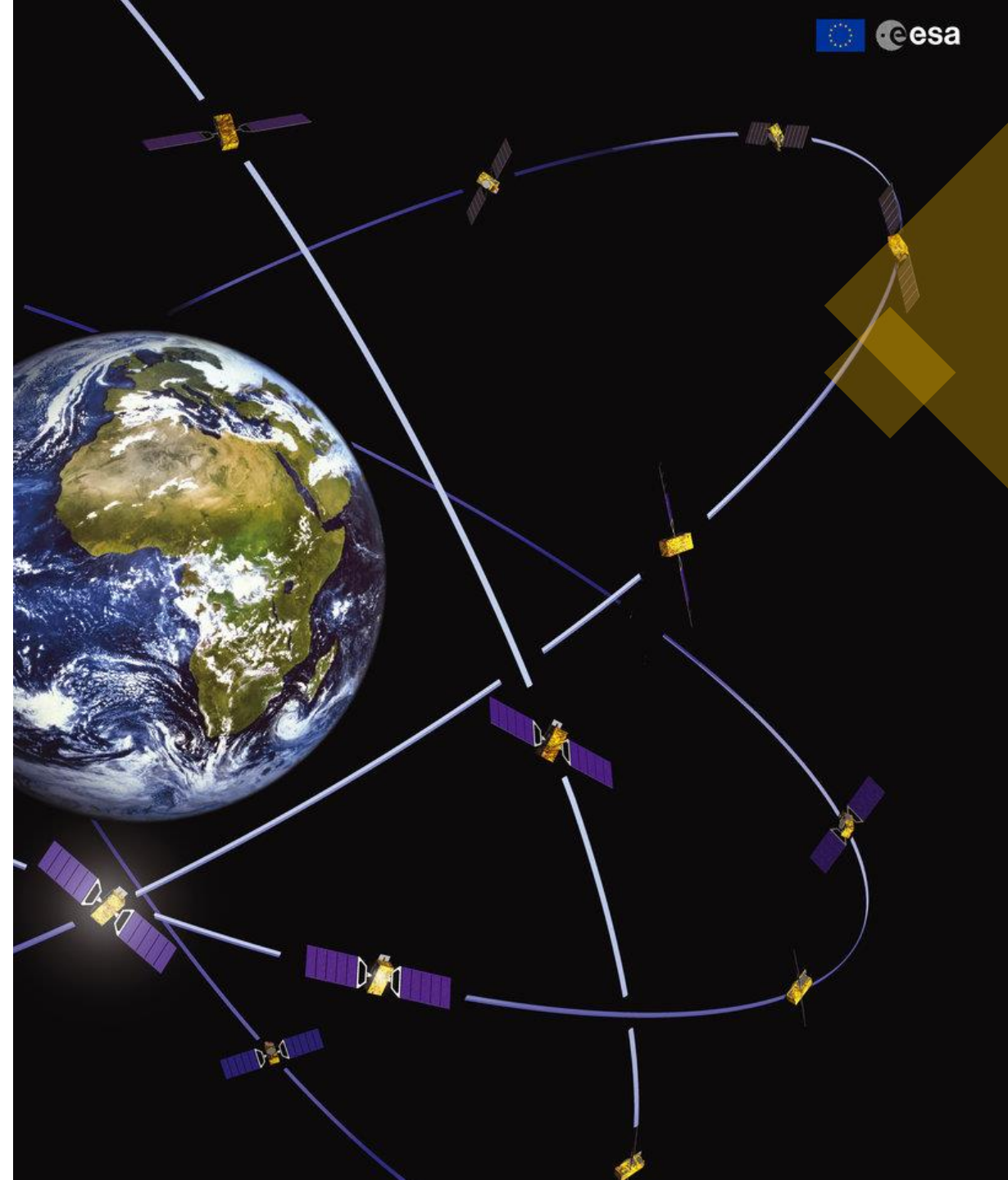
- ❑ **EARTH CARE / SVM** – Mass Memory and Formatting Unit
- ❑ **GAIA / SVM** – Payload Data Handling Unit
- ❑ **EXPERT** – Vehicle Memory Unit
- ❑ **SAR LUPE – DCSU** – Mass Memory board
- ❑ **KOMPSAT 2 – DCSU** - Mass Memory board
- ❑ **SOHO / VIRGO** – Data Acquisition System
- ❑ **XMM / RGS** – Data Acquisition System (incl. Formatting)

## Instrument Controllers / Mechanism Drives

- ❑ **FLEX - FLORIS** Instrument Control Unit
- ❑ **INSIGHT** – Seismometer Electronics Box
- ❑ **SENTINEL 1 / SES** – Instrument Control Module
- ❑ **AEOLUS** – Aladin Control and Data Management Unit
- ❑ **GOCE** - Gradiometer complete electronics (3xFEEU, GAIEU & TCEU)
- ❑ **IASI Ng** – Mechanism Drive Electronics
- ❑ **MTG / IRS** – Interferometer Control Electronics
- ❑ **BEPI-COLOMBO / BELA** – Analogue Electronic Unit

# NAVISP EL2 006 “Space GNSS Receiver”

- **Goal:** development of a high performance, COTS based GNSS receiver targeting satellite constellations
  - To Bridge gap between low-end and high-end solutions
  - For single LEO spacecraft and large LEO constellations
  - Competitive price to performance ratio
  - Basis platform for future evolutions
- **Main project outcome:**
  - Engineering Model of NAVILEO receiver



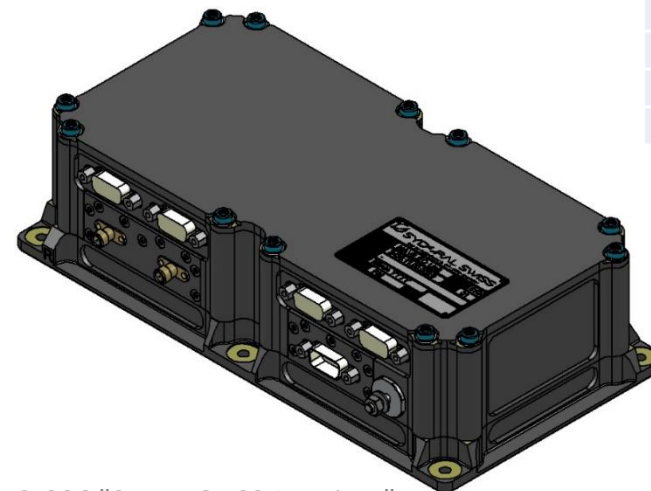
## NAVILEO receiver

### Advantages

- Based on rad-tolerant architecture & COTS EEE components ⇔ low recurrent price, suitable for small/mini/micro sat & mega-constellations
- High sensitivity ⇔ supports both active & passive antennas
- Multi-constellation & multi-frequency ⇔ high PVT availability even in GEO, HEO,...; high accuracy (iono-free combination solution)
- Onboard orbital propagator ⇔ Improved PVT perfo., sensitivity and availability
- In-flight FW/SW upgradability ⇔ upgradable (new signals, constellations, ...)
- Fugro Spacestar enabled ⇔ Real-time sub-dm (3D rms) POD on-demand

### Availability

- EM: Q2 2020
- FM Q4 2020



Performance characteristics	
Number of channels	48
Antenna inputs	1 (2 in option); supports both active and passive antenna(s)
Signals and frequ.	Galileo E1b and E5a GPS L1C/A and L5I/Q
Acquisition sensitivity (dBHz, for $P_d=0.9$ )	28 (L1); 31 (E1b)
Tracking sensitivity (dBHz)	20 (L1, E5a); 22 (L5); 24 (E1B)
Warm / cold TTFF <sup>1</sup>	< 20 s / < 100 s
Typical pos. accuracy <sup>1</sup>	< 5 m (3D rms)
PPS signal (RS-422)	< 50 ns (rms)
TM/TC	UART, CAN in option (other interfaces possible). Fully compliant with PUS/CCSDS standard.
Update rate	1 - 10 Hz
Physical characteristics (TBC)	
Power / voltage	8 W typical at 5 VDC
Mass	1300 gr
Dimension	219.5 x 110.5 x 59 mm <sup>3</sup>
Operating temperature	-20°C - +50 °C
Lifetime	Min. 5 years in LEO

<sup>1</sup>Tested in a typical LEO orbit, all SVs at 44 dB-Hz

Adv

Avai



- Proprietary global reference network supporting GPS, GLONASS, BEIDOU, & Galileo

- Orbit & Clock, Real time
- Position: < 10 cm
- Velocity: < 5 mm/s
- Time: < 5 ns

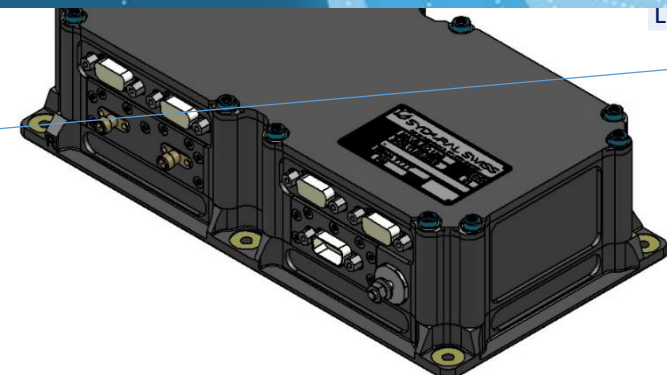
- High availability & redundancy
- Track record & SLA's

Lifetime

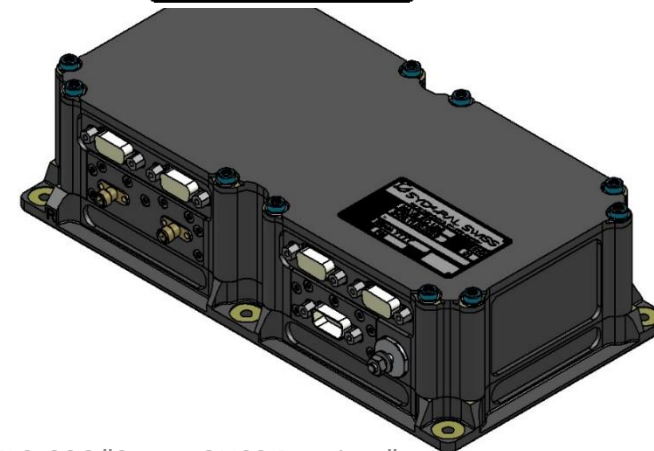
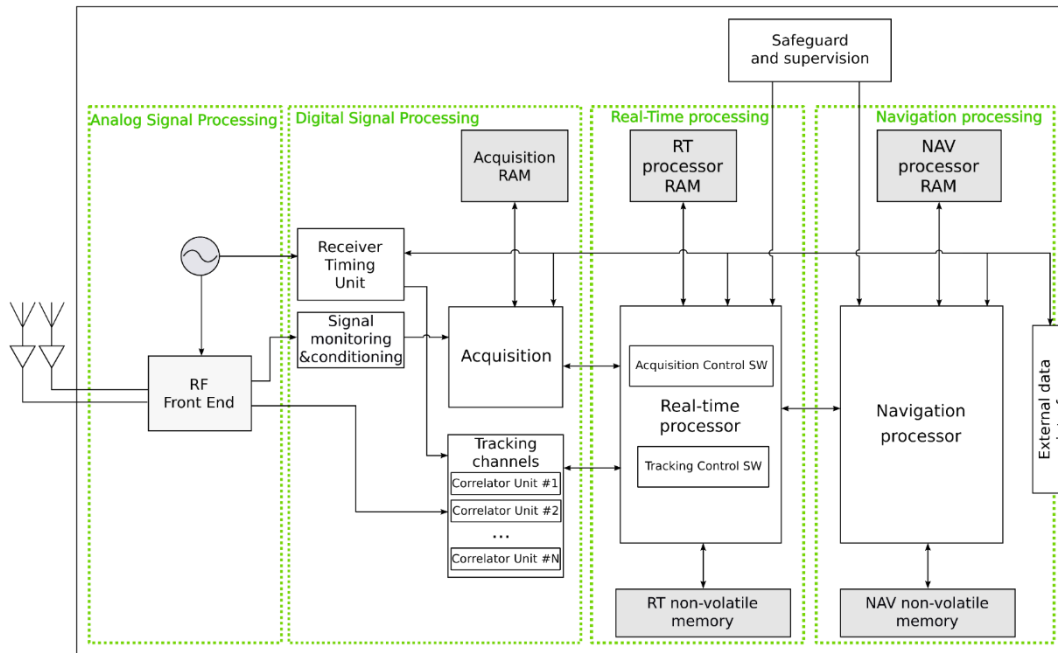
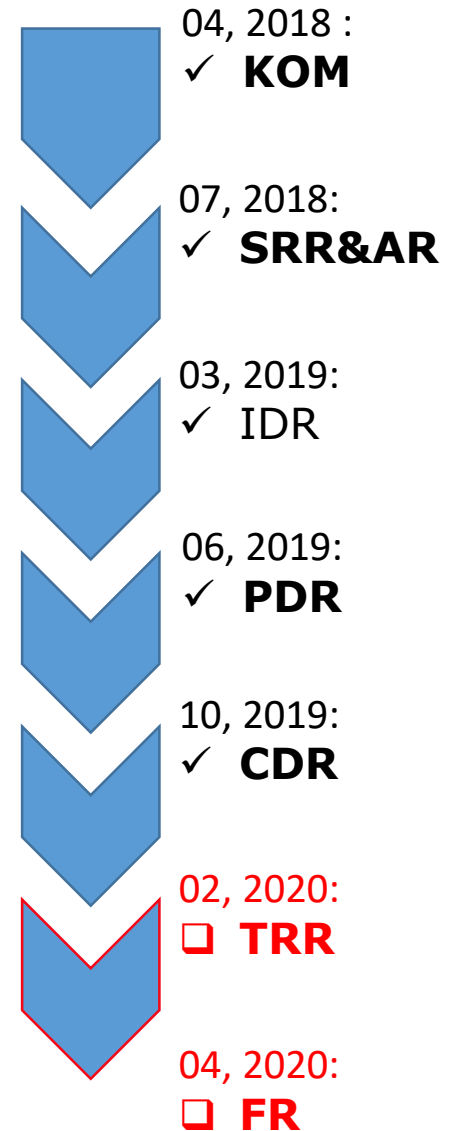
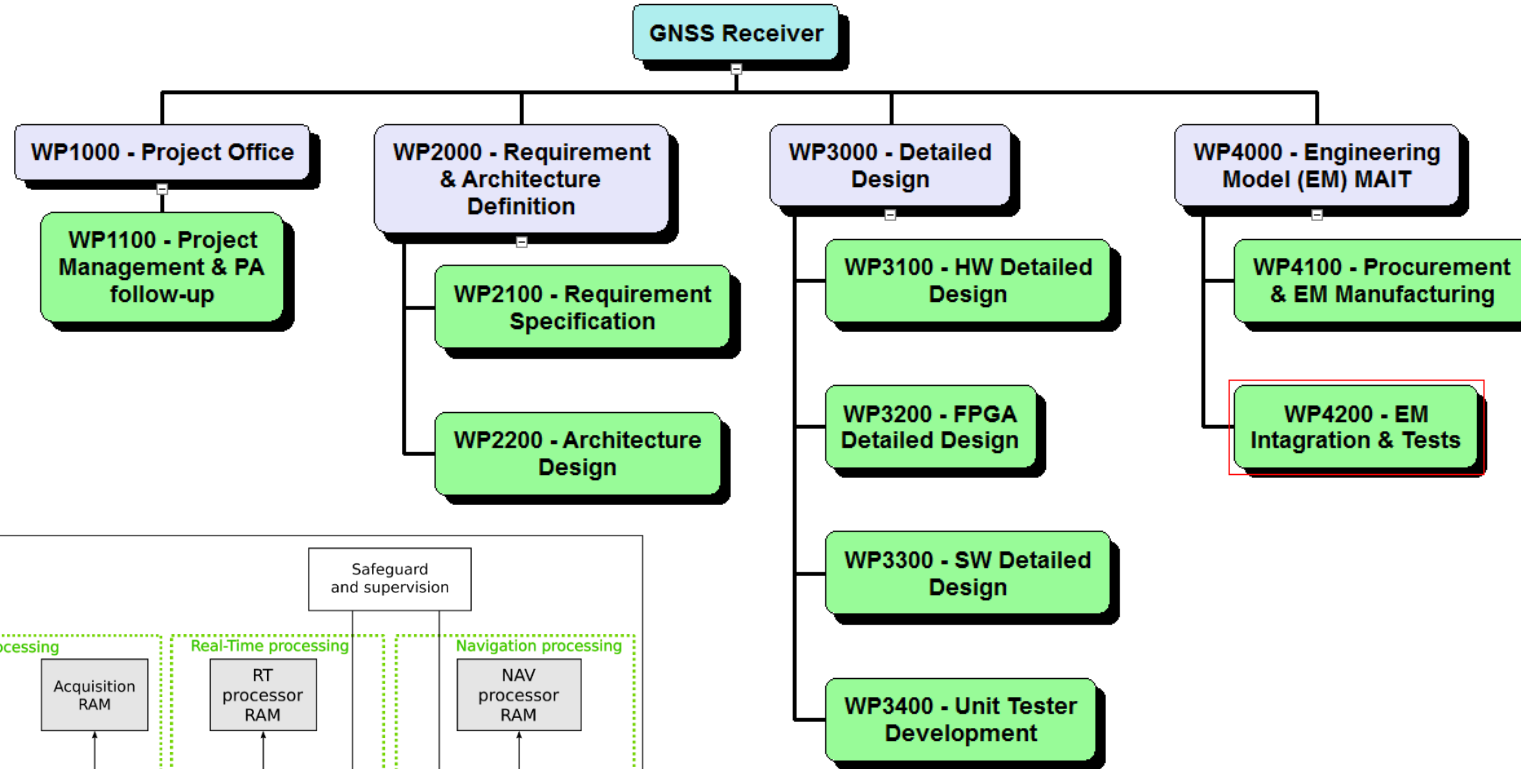
Min. 5 years in LEO

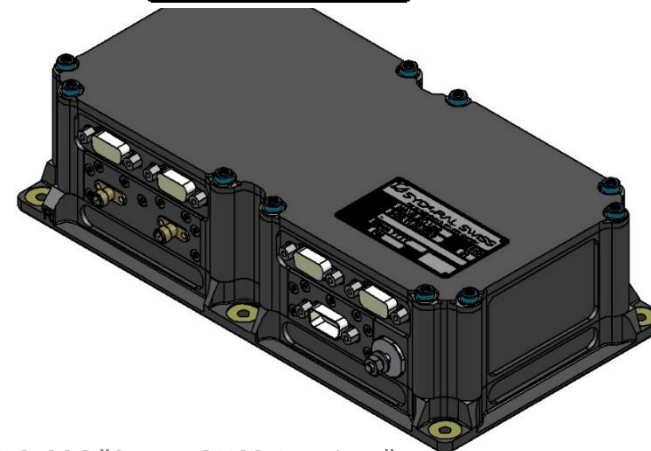
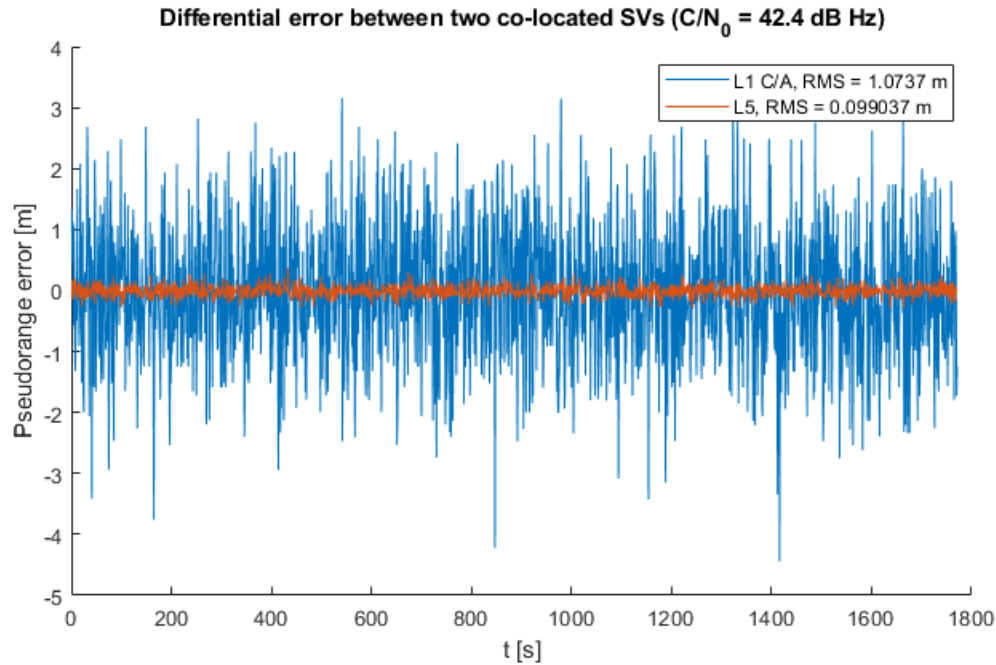
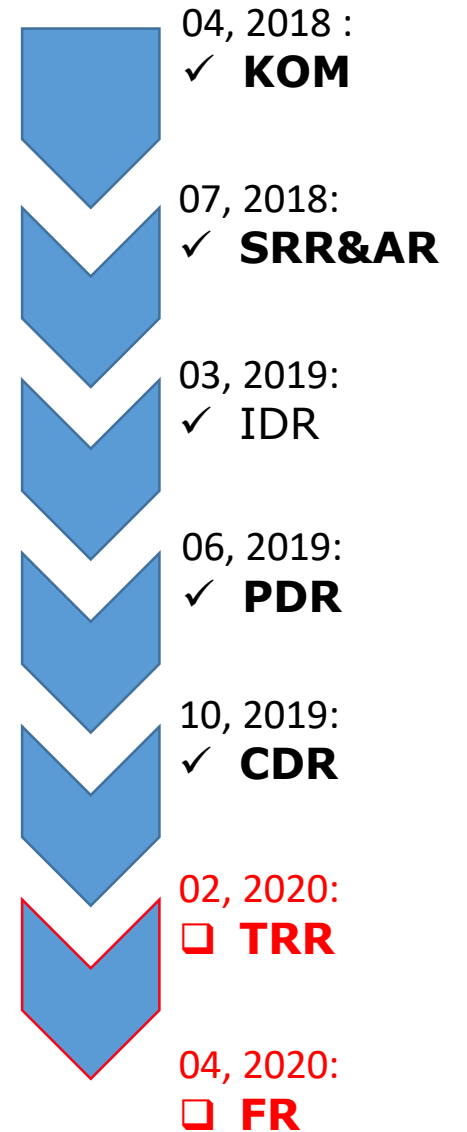
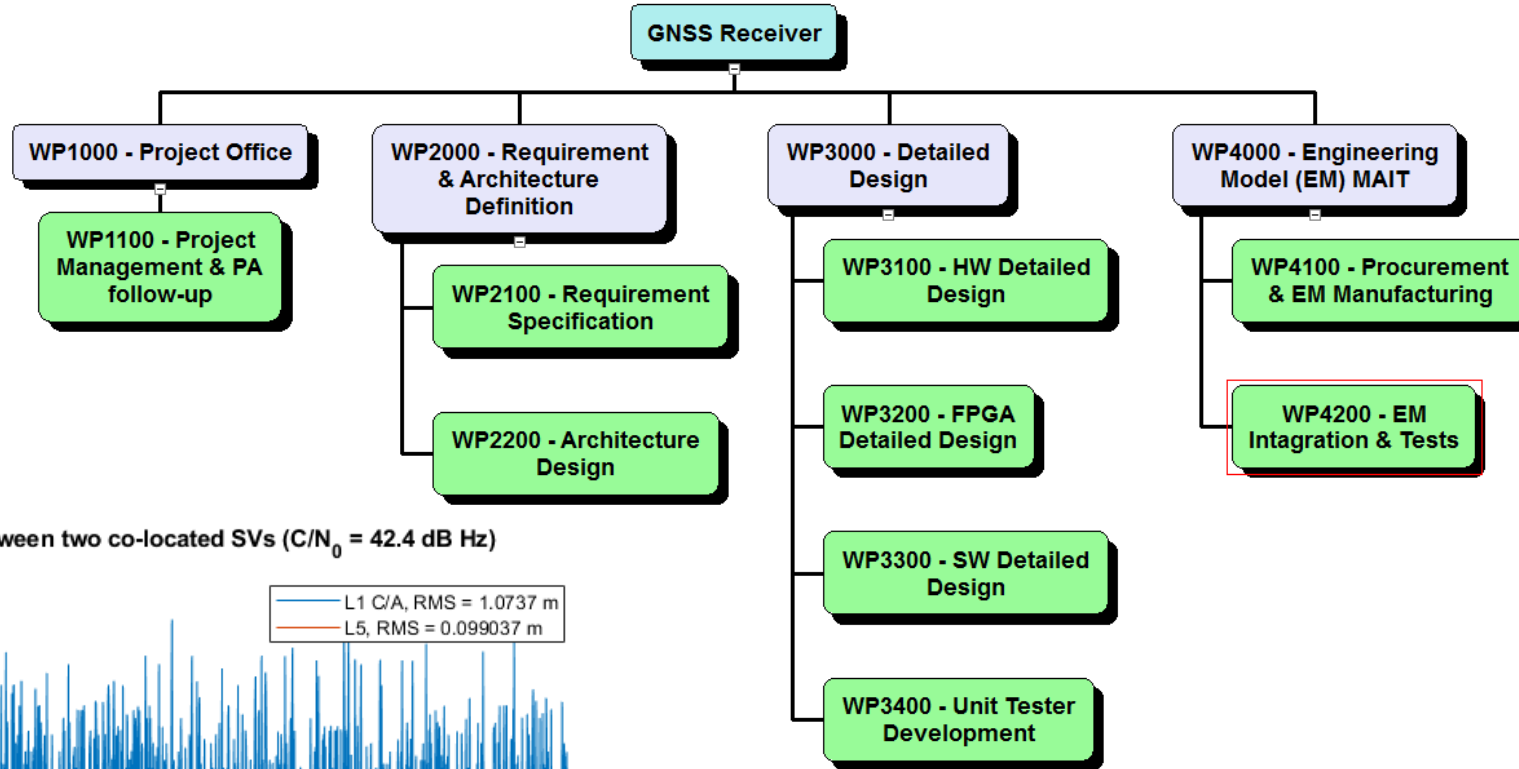
<sup>1</sup>Tested in a typical LEO orbit, all SVs at 44 dB-Hz

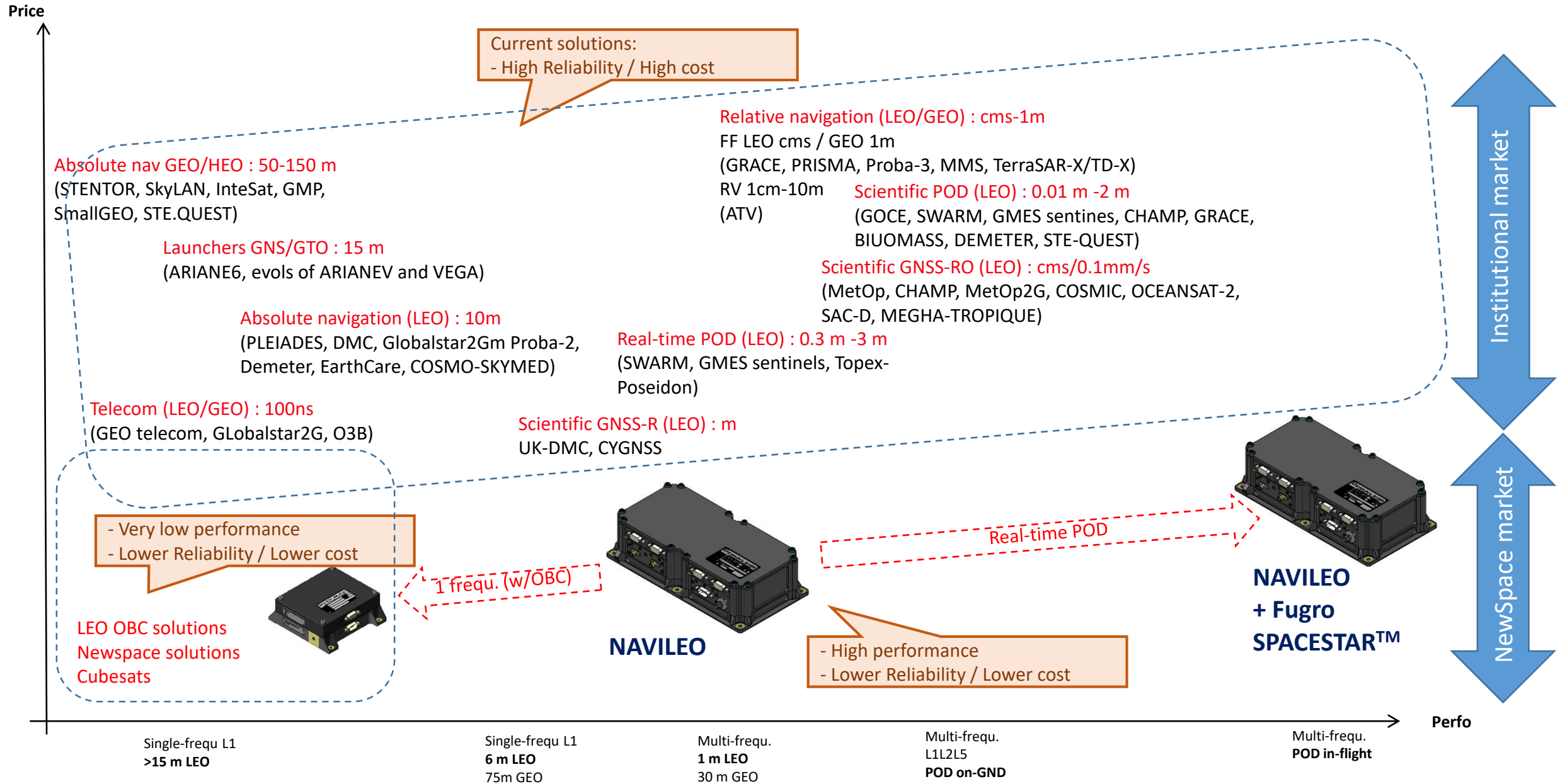
REAL TIME - ACCURATE POSITIONING
   
**SYSTEM ENABLED**



NAVISP-EL2-006 "Space GNSS Receiver"







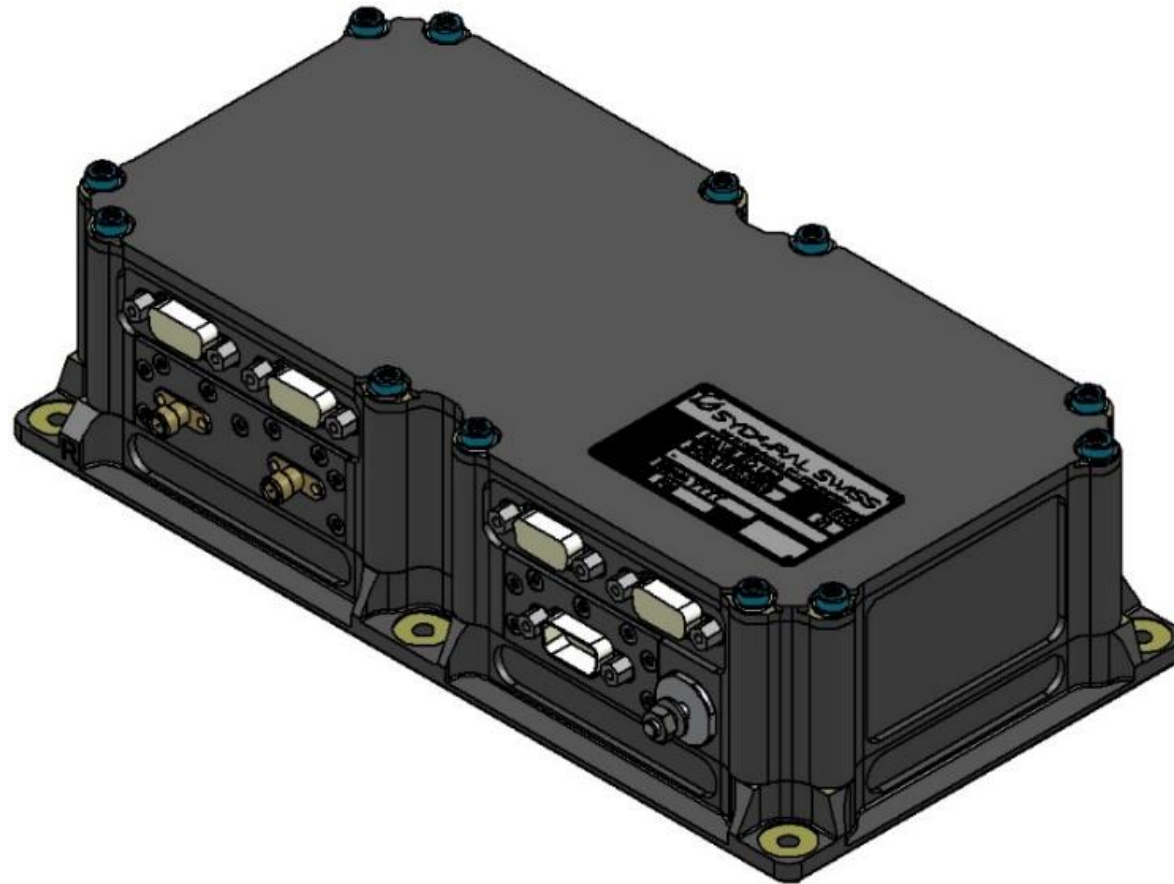
Step 1 : availability of NAVILEO's baseline version for Q2 2020 (EM) and Q3 2020 (PFM)

NAVILEO GALE1/E5a+GPSL1/L5

NAVILEO



High-performance GAL. E1/E5a + GPS L1/L5 space GNSS receiver for LEO spacecrafts



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Step 2: in parallel, additional developments of NAVILEO to target additional applications / market segments

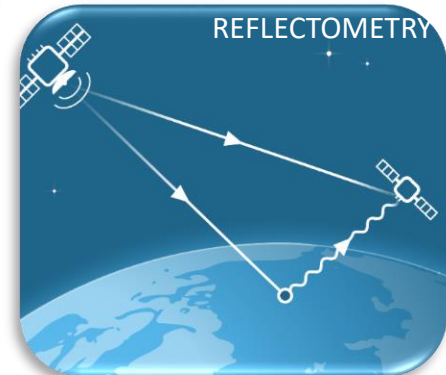
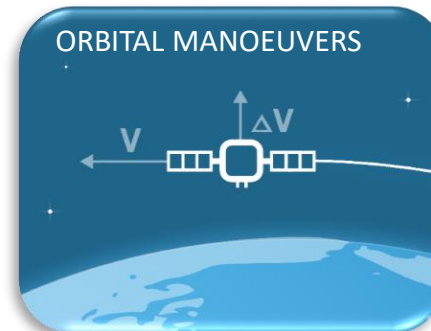
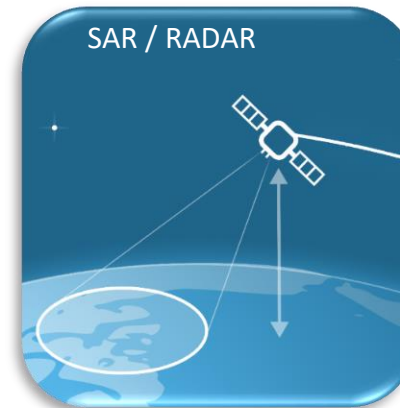
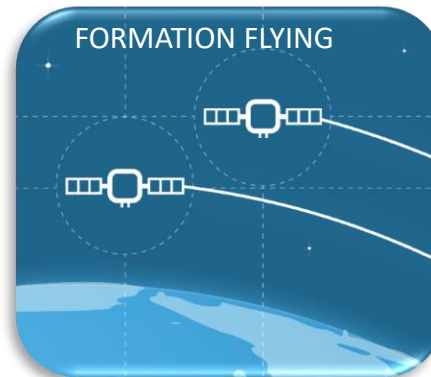
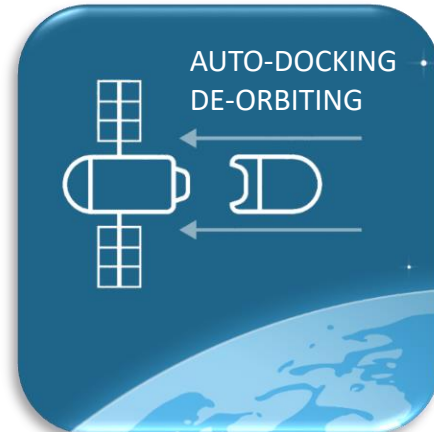
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Real-time on-board POD algorithms	+ Fugro Spacestar	For missions requiring < 10 cm 3D rms POD (real-time, absolute or relative)

## Application benefits:

- ✓ Fully integrated within NAVILEO (no need for additional antenna)
- ✓ No need to download GNSS raw data and post-processing via ground infrastructure
- ✓ Allows for real-time on-board data processing
- ✓ Reduced product latency

## POD Performance:

Position better than 10 cm 3D rms  
 Velocity better than 5 mm/s  
 Time better than 5 ns



Step 1 : availability of NAVILEO's baseline version for Q2 2020 (EM) and Q3 2020 (PFM)

NAVILEO GALE1/E5a+GPSL1/L5

NAVILEO

High-performance GAL. E1/E5a + GPS L1/L5 space GNSS receiver for LEO spacecrafts

Step 2: in parallel, additional developments of NAVILEO to target additional applications / market segments

Real-time on-board POD algorithms

+ Fugro Spacestar

For missions requiring <10 cm 3D rms POD (real-time, absolute or relative)

Implementation of very high sensitivity algorithms

NAVIMOON 

For more demanding missions in GTO, GEO, HEO, MTO, and to the Moon!

## NAVISP EI1-023 : NAVIMOON project

❑ Goal: development of a Moon GNSS receiver prototype (EM)

❑ Applications

- Autonomous navigation for Earth – Moon Transfer orbits
- Autonomous navigation for cislunar orbits
- More...

❑ Characteristics

- Based on NAVILEO + higher sensitivity + tightly coupled navigation filter (GNSS+OF) + ...

❑ Availability

- EM: Q1 2021



Image source: <https://www.esa.int/eseach?q=moon+village>

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Real-time on-board POD algorithms	+ Fugro Spacestar	For missions requiring <10 cm 3D rms POD (real-time, absolute or relative)
Implementation of very high sensitivity algorithms	NAVIMOON	For more demanding missions in GTO, GEO, HEO, MTO, and to the Moon!
Addition of GNSS signal re-generation capabilities	LEO-PNT →	For leveraging LEO mega-constellations as alternate GNSS providing secured position, navigation and time, or synchronization of payload to GNSS time

## LEO PNT demonstrator : NAVILEO receiver + POD SW + GALILEO-like signal re-generator and transmitter

### Applications

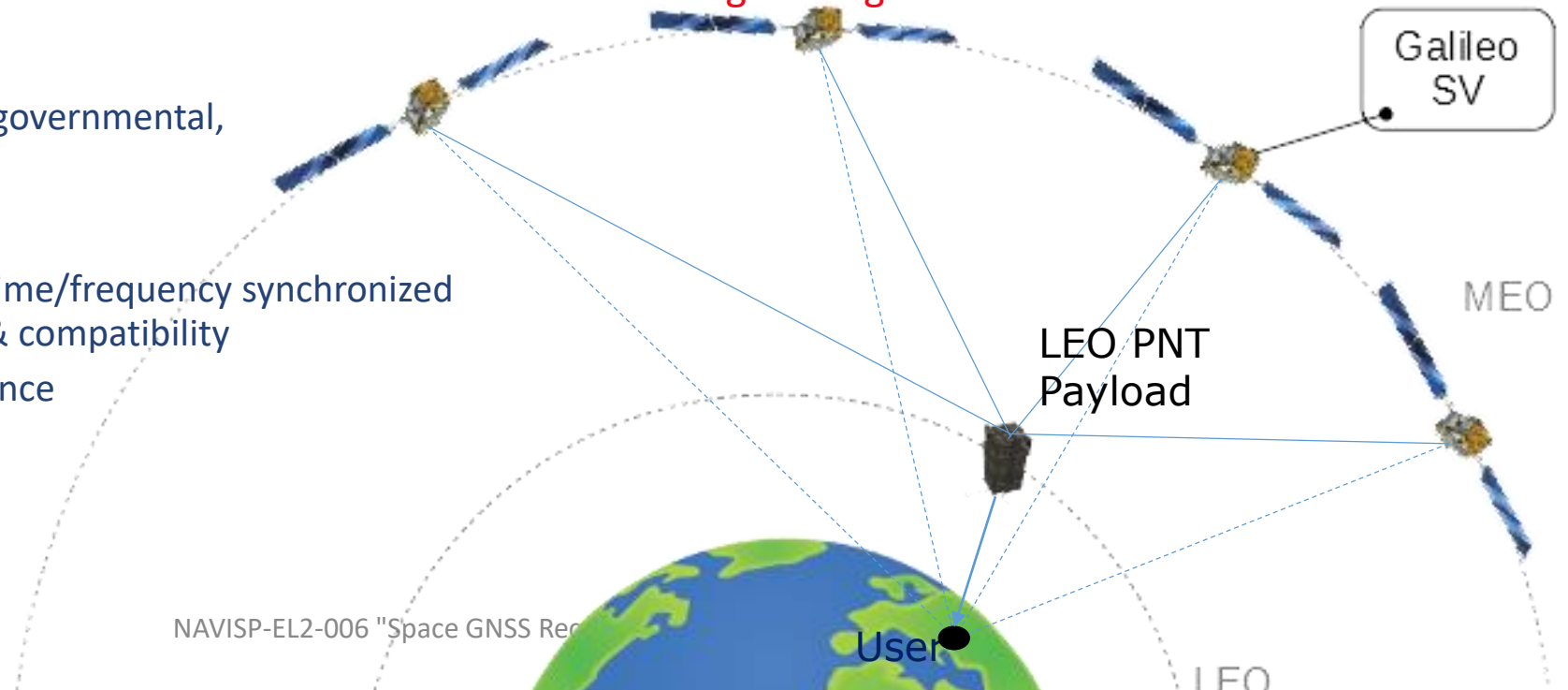
- Alternate LEO PNT constellation for governmental, IoT, road transportation users

### USP & Differentiators

- POD solution + signal regeneration time/frequency synchronized with GNSS time ⇔ interoperability & compatibility
- High dynamics ⇔ Fast PPP convergence
- Alternate PNT ⇔ more security
- Stronger signals ⇔ IoT

### Availability

- Demonstrator : Q2 2020



## □ NAVISP EL. 2 benefits

### ○ Very flexible and effective programmatic Element 2 framework:

- ESA/SME co-funded scheme
- ➔ Enables company to propose a project and define the product specifications, ...
- ➔ Ownership of developed IP remains to Industry
- ➔ Fast submission & feedback process

### ○ Great ESA support:

- ✓ Project follow-up and constructive feedback/guidance through regular progress meetings & milestones
- ✓ Access to some of ESA facilities / experts
- ✓ Proposed a full evaluation of our final product (EM) at the end of the project

➔ Enabled the creation of a new GNSS product line in Syderal!  
from LEO ➔ to LEO PNT ➔ to MOON applications!



## Acknowledgments:

- Swiss ESA delegation (Swiss Space Office)
- NAVISP P.O. (A. Fiumara and P. Manchini)
- Our ESA Project Officer (Pietro Giordano)
- My colleagues in Syderal



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